

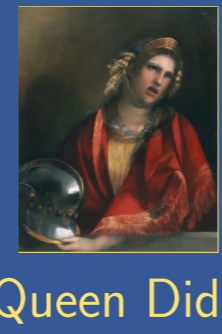


# The Reverse Isoperimetric Inequalities for Strictly Convex Domains

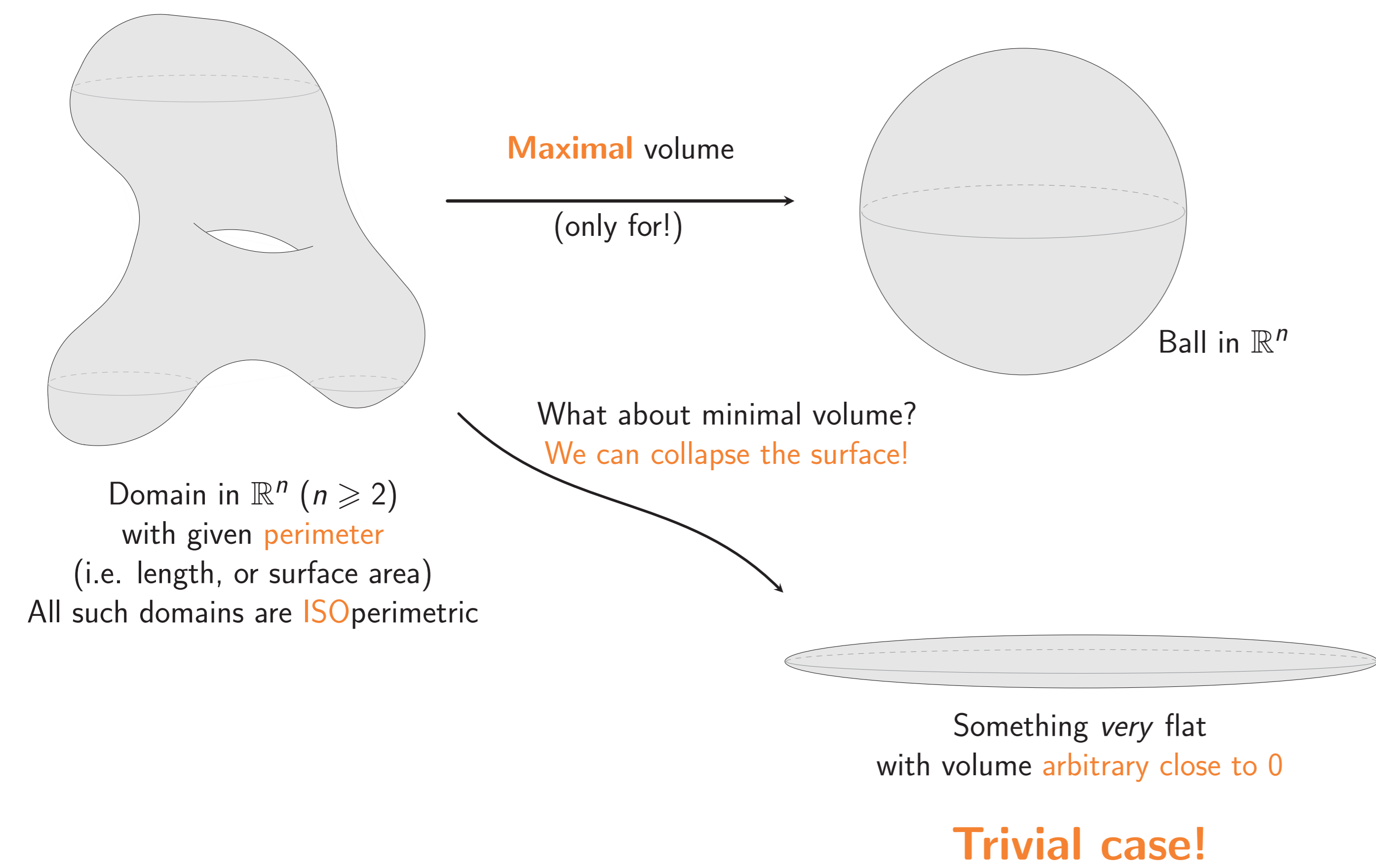
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## The classical isoperimetric inequality (Dido's Problem)



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### Precise statements

#### Theorem (Solution of Dido's Problem)

Suppose a closed surface  $\Sigma \subset \mathbb{R}^n$  and a sphere  $S \subset \mathbb{R}^n$  have equal perimeters (length/surface areas)

$$\text{Perimeter}(\Sigma) = \text{Perimeter}(S),$$

then

$$\text{Volume}(\Sigma) \leq \text{Volume}(S),$$

where  $\text{Volume}(\cdot)$  is the volume of the domain enclosed by the corresponding surface. Moreover, equality holds only if  $\Sigma = S$ .

Equivalent statement for  $\mathbb{R}^2/\mathbb{R}^3$ .

#### Theorem (Isoperimetric inequality)

( $\mathbb{R}^2$ ) Let  $L$  and  $A$  be the length of the boundary and the area of a plane domain; then

$$4\pi A \leq L^2,$$

and equality holds only if the domain is a disc.

( $\mathbb{R}^3$ ) Let  $A$  and  $V$  be the surface area of the boundary and the volume of a domain in  $\mathbb{R}^3$ ; then

$$36\pi V^2 \leq A^3,$$

with equality only if the domain is a ball.

### Reversing and what is known about it?

Restricting **curvature** of the boundary of a domain, we can obtain a **non-trivial reverse isoperimetric inequality**.

In [6], [5] authors investigated the reverse isoperimetric problem for curves in  $\mathbb{R}^2$  ([6]) and, partially, surfaces in  $\mathbb{R}^3$  ([5]) with curvatures  $|k| \leq 1$  (in a weak sense). Such a bound allows curves and surfaces to be **non-convex**, and for such classes the reverse isoperimetric problem is not well-defined.

We consider **convex curves and surfaces with restricted curvature**.

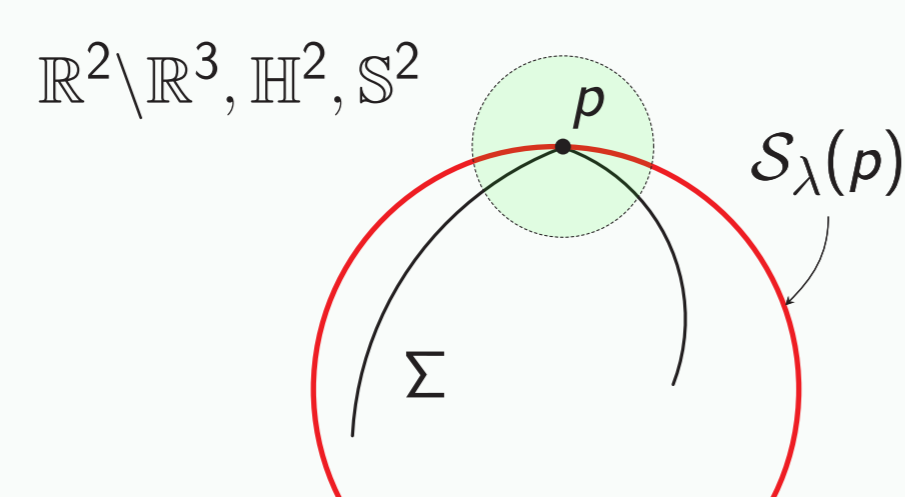
### What do we mean by restricting curvature?

For simplicity, we focus only on the objects in the spaces where the results are known so far. That is, we will consider **curves in 2-dimensional constant curvature spaces** — hyperbolic space  $\mathbb{H}^2$  of curvature  $-1$ , Euclidean plane  $\mathbb{R}^2$  of curvature  $0$ , sphere  $\mathbb{S}^2$  of curvature  $1$ , — and **surfaces in  $\mathbb{R}^3$** .

### Definition of $\lambda$ -convexity

A locally convex hypersurface  $\Sigma$  is called  **$\lambda$ -convex** (with  $\lambda > 0$ ) if for any point  $p \in \Sigma$  there exists a curve/surface  $S_\lambda(p)$  of constant curvature  $\lambda$  passing through  $p$  in such a way, that in some neighborhood of  $p$  the surface  $\Sigma$  lies inside  $S_\lambda(p)$ .

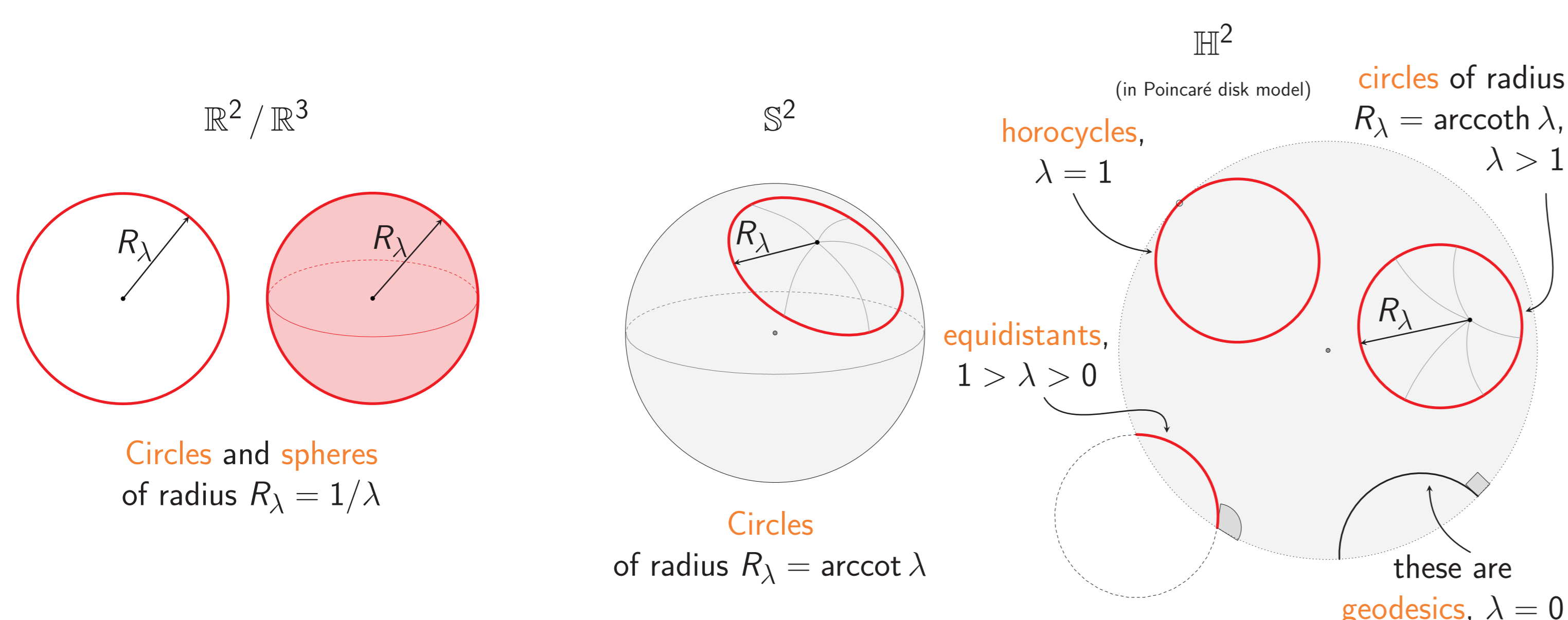
**$\lambda$ -convex domain**, by definition, is a domain with  $\lambda$ -convex boundary.



**Informally:** a curve/surface is  $\lambda$ -convex if it bends **not slower** than the curve/surface of constant curvature  $\lambda$ .

**In the smooth case:** if  $\Sigma$  is **smooth  $\lambda$ -convex curve**, then its curvature at each point satisfies  $k \geq \lambda$  (in the case of surfaces,  $k$  is the normal curvature).

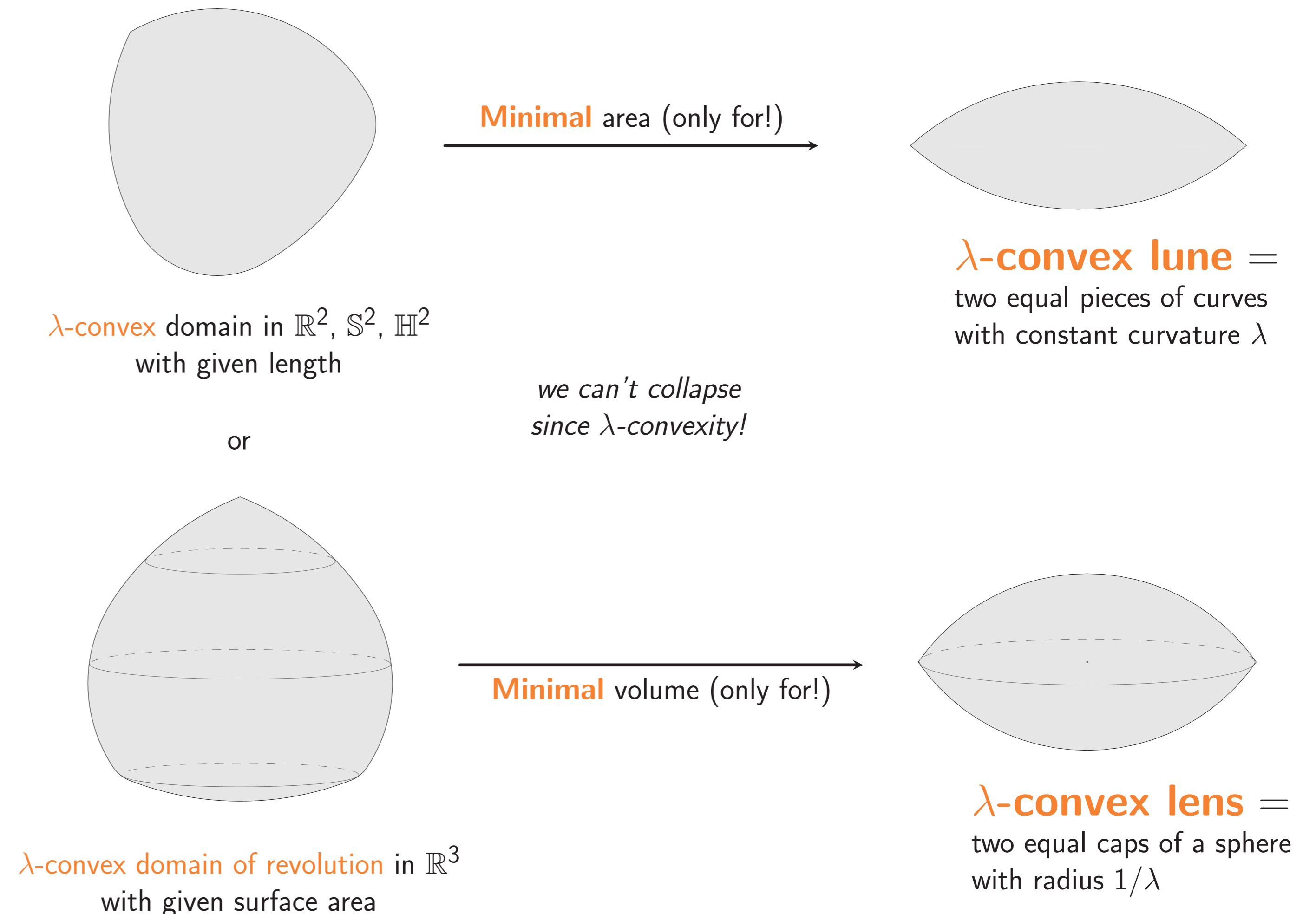
### What are the curves and surfaces of constant curvature?



## The reverse isoperimetric inequality (Reverse Dido's Problem)



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### Precise statements

#### Theorem ([1, 3, 2], Solution of Reverse Dido's Problem in 2-dim constant curvature spaces)

Let  $\Sigma$  be a closed embedded  $\lambda$ -convex curve lying in  $\mathbb{R}^2, \mathbb{S}^2$ , or  $\mathbb{H}^2$ . If  $\Sigma_\lambda$  is a  $\lambda$ -convex lune such that

$$\text{Perimeter}(\Sigma) = \text{Perimeter}(\Sigma_\lambda),$$

then

$$\text{Volume}(\Sigma) \geq \text{Volume}(\Sigma_\lambda).$$

Moreover, equality holds if and only if  $\Sigma$  is a  $\lambda$ -convex lune.

#### Theorem ([4], Partial solution of the Reverse Dido's Problem in $\mathbb{R}^3$ )

Let  $\Sigma \subset \mathbb{R}^3$  be a complete  $\lambda$ -convex surface of revolution. If  $\Sigma_\lambda \subset \mathbb{R}^3$  is a  $\lambda$ -convex lens such that

$$\text{Perimeter}(\Sigma) = \text{Perimeter}(\Sigma_\lambda),$$

then

$$\text{Volume}(\Sigma) \geq \text{Volume}(\Sigma_\lambda),$$

and equality is attained if and only if  $\Sigma$  is congruent to  $\Sigma_\lambda$ .

The theorems above are equivalent to the following.

#### Theorem (Reverse isoperimetric inequality)

( $\mathbb{R}^2, \mathbb{S}^2, \mathbb{H}^2$ ) Let  $\Sigma$  be a closed embedded  $\lambda$ -convex curve of length  $L$  and enclosing a domain of area  $A$ .

1. If  $\Sigma \subset \mathbb{R}^2$ , then

$$A \geq \frac{L}{2\lambda} - \frac{1}{\lambda^2} \sin \frac{L\lambda}{2}.$$

2. If  $\Sigma \subset \mathbb{S}^2$ , then

$$A \geq 4 \arctan \left( \frac{\lambda}{\sqrt{\lambda^2 + 1}} \tan \left( \frac{\sqrt{\lambda^2 + 1}}{4} L \right) \right) - \lambda L.$$

3. If  $\Sigma \subset \mathbb{H}^2$ , and  $\lambda > 1$ , then

$$A \geq \lambda L - 4 \arctan \left( \frac{\lambda}{\sqrt{\lambda^2 - 1}} \tan \left( \frac{\sqrt{\lambda^2 - 1}}{4} L \right) \right).$$

4. If  $\Sigma \subset \mathbb{H}^2$ , and  $\lambda = 1$ , then

$$A \geq L - 4 \arctan \frac{L}{4}.$$

5. If  $\Sigma \subset \mathbb{H}^2$ , and  $1 > \lambda > 0$ , then

$$A \geq \lambda L - 4 \arctan \left( \frac{\lambda}{\sqrt{1 - \lambda^2}} \tanh \left( \frac{\sqrt{1 - \lambda^2}}{4} L(\gamma) \right) \right).$$

Equality holds only for a  $\lambda$ -convex lune.

( $\mathbb{R}^3$ , rotational case) Suppose  $\Sigma \subset \mathbb{R}^3$  is a complete  $\lambda$ -convex surface of revolution,  $V$  and  $A$  are the volume of the domain enclosed by  $\Sigma$  and the surface area of  $\Sigma$ , respectively; then

$$96\pi^2 V \geq \lambda A^2 (12\pi - \lambda^2 A),$$

and equality holds if and only if  $\Sigma$  is a  $\lambda$ -convex lens.

### Open problems

The result in  $\mathbb{R}^3$  above is **the only known result** on the solution of Reverse Dido's Problem in higher dimensions so far. The following conjecture is very plausible.

#### Conjecture (due to A. Borisenko)

For the spaces of constant curvature the solution for the analogous multi-dimensional reverse isoperimetric problem in the class of complete  $\lambda$ -convex hypersurfaces is a convex joint of two equal totally umbilical caps of normal curvature equal to  $\lambda$  (**lens hypersurface**).

### References

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